Accord CONTROLS<br>APEX A9000 Digital Positioner

# Installation Operation <br> Maintenance 

FCD ACENIM0132-01

### 1.1 Using

The following instructions are designed to assist in unpacking, installing and performing maintenance as required on FLOWSERVE products. Product users and maintenance personnel should thoroughly review this bulletin prior to installing, operating or performing any maintenance. In most cases FLOWSERVE valves, actuators and accessories are designed for specific applications (e.g. with regard to medium, pressure, temperature). For this reason they should not be used in other applications without first contacting the manufacturer.

### 1.2 Terms concerning safety

The safety terms DANGER, WARNING, CAUTION and NOTE are used in these instructions to highlight particular dangers and/ or to provide additional information on aspects that may not be readily apparent.

DANGER: indicates that death, severe personal injury and/or substantial property damage will occur if proper precautions are not taken.

WARNING: indicates that death, severe personal injury and/or substantial property damage can occur if proper precautions are not taken.

CAUTION: indicates that minor personal injury and/or property damage can occur if proper precautions are not taken.

!NOTE: indicates and provides additional technical information, which may not be very obvious even to qualified personnel.

Compliance with other, not particularly emphasised notes, with regard to trans- port, assembly, operation andmaintenance and with regard to technical documentation (e.g. in the operating instruction, product documentation or on the product itself) is essential, in order to avoid faults, which in themselves might directly or indirectly cause severe personal injury or property damage.

### 1.3 Protective clothing

FLOWSERVE products are often used
in problematic applications (e.g. extremely high pressures, dangerous, toxic or corrosive mediums). In particular valves with bellows seals point to such applications. When performing service, inspection or repair operations always ensure, that the valve and actuator are depressurised and that the valve has been cleaned and is free from harmful substances. In such cases pay particular attention to personal protection(protective clothing, gloves, glasses etc.).

### 1.4 Qualified personnel

Qualified personnel are people who, on account of their training, experience and instruction and their knowledge of relevant standards, specifications, accident prevention regulations and operating conditions, have been authorised by those responsible for the safety of the plant to perform the necessary work and who can recognise and avoid possible dangers.

### 1.5 Installation

DANGER: Before installation check the order-no, serial-no. and/ or the tag-no. to ensure that the valve/actuator is correct for the intended application.
Do not insulate extensions that are provided for hot or cold services.
Pipelines must be correctlyaligned to ensure that the valve is not fitted under tension.

Fire protection must be provided by the user.

### 1.6 Spare parts

Use only FLOWSERVE original spare parts. FLOWSERVE cannot accept responsibility for any damages that occur from using spare parts or fastening materials from other manufactures. If FLOWSERVE products (especially sealing materials) have been on store for longer periods check these for corrosion or deterioration before using these products. Fire protection forFLOWSERVE products must beprovided by the end user.

### 1.7 Service / repair

To avoid possible injury to personnel or damage to products, safety terms must be strictly adhered to. Modifying this product, substituting non-factory parts, or using maintenance procedures other than outlined in this instruction could drastically affect performance and be hazardous to personnel and equipment, and may void existing warranties. Between actuator and valve there are moving parts. To avoid injury FLOWSERVE provides pinch-pointprotection in the form of cover plates, especially where side-mounted positioners are fitted. If these plates are removed for inspection, service or repair special attention is required. After completing work the cover plates must be refitted.

Apart from the operating instructions and the obligatory accident prevention directives valid in the country of use, all recognised regulations for safety and good engineering practices must be followed.

## WARNING:

Before products are returned to FLOWSERVE for repair or service FLOWSERVE must be provided with a certificate which confirms that the product has been decontaminated and is clean. FLOWSERVE will not accept deliveries if a certificate has not been provided (a form can be obtained from FLOWSERVE).

### 1.8 Storage

In most cases FLOWSERVE products are manufactured from stainless steel. Products not manufactured from stainless steel are provided with an epoxy resin coating. This means that FLOWSERVE products are wellprotected from corrosion. Nevertheless FLOWSERVE products must be stored adequately in a clean, dry environment. Plastic caps are fitted to protect the flange faces to prevent the ingress of fo- reign materials. If the positioner must be stored outdoors, it is important that all the cover screws are tightened and that all connections and ports are properly sea-led. Replace shipping plugs with proper plugs and do not leave ports open and facing upwards.

### 1.9 Valve and actuator variations

These instructions cannot claim to cover all details of all possible productvariations, nor in particular can they provide information for every possibleexample of installation, operation or maintenance. This means that the instructions normally include only the directions to be followed by qualified personal where the product is being used for is defined purpose. If there are any uncertainties in this respect particularly in the event of missing product-related information, clarification must be obtained via the appropriate FLOWSERVE sales office.

## 2. Unpacking

Each delivery includes a packing slip. When unpacking, check all delivered valves and accessories using this packing slip. Report transport damage to the carrier immediately. In case of discrepancies, contact your nearest FLOWSERVE location.

## 3. Certificates

Please note that a full copy of certificates and approvals for Intrinsically safe and Explosion proof applications can be downloaded in pdf format from our web page:
http://www.flowserve.com

## 4. APEX A9000 Overview

The Apex A9000 is a two-wire looppowered, $4-20 \mathrm{~mA}$ input digital valve positioner.
The Apex A9000 positioner controls actuators with rotary mountings.
The Apex A9000 is completely powered by the $4-20 \mathrm{~mA}$ input signal. The minimum input signal required to function is $3,6 \mathrm{~mA}$. As an option the D20 can be equipped with HART protocol to allow bidirectional communication.

Since the positioner is insensitive to supply pressure changes and can handle supply pressures from 1,5 to 6 barg ( 22 to 105 psig), a supply regulator is usually not required; however, in applications where the supply pressure is higher than the maximum actuator pressure rating a supply regulator is required to lower the pressure to the actuator's maximum ra- ting (not to be confused with operating range). A coalescing air filter is recommended for all applications due to the close tolerances in the positioner.

Apex A9000 positioner accessories:Optional analog feedback system as well as limit switch unit and a directly attachable double acting module.

NOTE: The air supply must conform to ISA 7.0 .01 or IEC 770 (a dew point at least $10^{\circ} \mathrm{C} / 18^{\circ} \mathrm{F}$ below ambient temperature, particle size below five microns - one micron recommended - and oil content not to exceed one part per million).

## 5. Specifications

### 5.1 Technical data

Input signal
Current supply Max.
Load Standard
Voltage dropStandard 20mA Angle of rotation min
Angle of rotation Max
Air supply range
Out put
Air supply quality
Air supply effect Ingress protection
Operating humidity
Air connections
Cable entry
Terminals
Operating Temperature
Storage temperature
Air delivery capacity
Air delivery capacity Double acting
Air consumption Single acting
Air consumption Double acting
Cv air delivery Single acting
Cv air delivery Double acting
Cut off function
Linearity
Sensitivity
Resolution
Repeatability
Hysteresis + dead band
Temp effect
Mounting position effect
CE
Approvals

Certificate nr
Housing material Surface treatment
Soft goods
Weight

4-20 mA Current supply min. $\quad 3,6 \mathrm{~mA}$ 150 mA
400 ohm at 20 mA Load HART 470 ohm at 20 mA
8 VDC at 20 mA Voltage drop HART 9.4 VDC at
$0-40^{\circ}$
$0-90^{\circ}$
1.5-6 bar
$0-100 \%$ of air supply pressure
Free from oil, dust and moisture IEC 770,
ISA 7.0.01
$<0.1 \%$ FS for $10 \%$ pressure change at 6 Bar
IP66 / Nema 4X
$0-100 \%$ rh non-condensing
1/4" NPT
2 x 1/2" NPT or 2 x M20x 1,5
Screw terminals $2,5 \mathrm{~mm}^{2}$ (AWG 14)
-20 to $+85^{\circ} \mathrm{C}-40$ to $+85^{\circ} \mathrm{C}$ (optional)
-40 to $+85^{\circ} \mathrm{C}$
$7 \mathrm{Nm}^{3} / \mathrm{h}$ @ 6 bar (3 bar diff pressure)
$7 \mathrm{Nm}^{3} / \mathrm{h}$ @ 6 bar (3 bar diff pressure)
0,120 Nm³/h @ 6 bar
0,120 Nm³/h @ 6 bar
0,12
0,12
Close 0.5\% Open 99.5\%
$<1 \%$
<0.05\%
<0,1\%
<0.2\%
<0.5\%
<0.1\%/10K
<0,2\%
93/68/EEC, 2004/108/EEC, 2006/95/EEC
Ex II G Ex ia IIC T4 Ta: $85^{\circ} \mathrm{C}$
Class I Division 2 Groups A,B,C,D T4 non-incendive with fieldwiring Class I Division 2 IIC T4 non-incendive with fieldwiring
I.S. Class I Division 1 Groups A,B,C,D T4
I.S. Aex ia IIC T4

Nemko 08ATEX1362X
Die cast Aluminium
Powder coating
Nitrile
$1,5 \mathrm{~kg}$ (3.0 kg Explosion proof version)

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### 5.2 Limit switches

| Type | SPDT |
| :---: | :---: |
| Size | Sub Sub miniature |
| Rating | 3A, 125 VAC / 2A, 30VDC |
| Mechanical life | $>1 \times 10^{6}$ operations |
| Namur sensors |  |
| Type | P+F NJ2 V3 N Inductive DIN 19234 |
| Load current | $<1 \mathrm{~mA}>3 \mathrm{~mA}$ |
| Voltage range | 5-25 VDC |
| Hysteresis | 3-15\% (5\% typical) |
| Temp range | $-25^{\circ}$ to $+100^{\circ} \mathrm{C}\left(-248^{\circ}\right.$ to $\left.373^{\circ} \mathrm{F}\right)$ |
| Namur sensors |  |
| Type | P+F SJ2-N |
| Normal Voltage | 8 VDC |
| Load current | $1 \mathrm{~mA}<1<3 \mathrm{~mA}$ |
| Voltage range | (5-25 VDC) |
| Hysteresis (max) | 0.2\% |
| Temp range | $-25^{\circ}$ to $+100^{\circ} \mathrm{C}\left(-248^{\circ}\right.$ to $\left.373^{\circ} \mathrm{F}\right)$ |
| Namur sensors |  |
| Type | P+F SJ2-SN |
| Normal Voltage | 8 VDC |
| Load current | $1 \mathrm{~mA}<1<3 \mathrm{~mA}$ |
| Voltage range | 5-25 VDC |
| Hysteresis (max) | (0.2\%) |
| Temp range | $-40^{\circ}$ to $+100^{\circ} \mathrm{C}\left(-233^{\circ}\right.$ to $\left.373^{\circ} \mathrm{F}\right)$ |
| Namur sensors |  |
| Type | P+F SJ2-S1N |
| Normal Voltage | 8 VDC |
| Load current | $1 \mathrm{~mA}<1<3 \mathrm{~mA}$ |
| Voltage range | 5-25 VDC |
| Hysteresis (max) | 0.2\% |
| Temp range | $-25^{\circ}$ to $+100^{\circ} \mathrm{C}\left(-248^{\circ}\right.$ to $\left.373^{\circ} \mathrm{F}\right)$ |
| Proximity switches |  |
| Type | SPDT |
| Rating | 10W |
| Voltage max | 200VDC |
| Current max | 500mA |
| Contact resistance max | 0.2 ohm |
| Operating time | 1.0 ms |
| Transmitter |  |
| Power supply | 12-28 VDC |
| Output | 1-22 mA |
| Resolution | 0.1\% |
| Linearity | $\pm 0.5 \%$ |
| Load impedance | 600 ohm at (12 VDC and 20mA) |
| Alarm Output |  |
| Supply | 3-28 VDC |
| Output | 20mA @ 24 VDC |

### 5.3 Type sign



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### 5.4 APEX A9000 Model Code

## $\square$ BRAND

AC - Accord Black Polyester Paint
$\square$ MODEL
90 - Digital Positioner, Single Button Interface, LED Status
92 - Digital Positioner, Full LCD Menu, LED Status
$\square$ APPROVAL, CERTIFICATIONS
G - General Purpose
I - Intrinsically Safe, ATEX/FM
N - Class I Division 2, Non-incendive, with Fieldwiring
E - Explosionproof, ATEX/FM
$\square$ CONNECTIONS, AIR/ELECTRICAL
M $-1 / 4 /{ }^{\prime \prime}$ NPT Air, M $20 \times 1.5$ Electrical
N - $1 / 4^{\prime \prime}$ NPT Air, $1 / 2^{\prime \prime}$ NPT Electrical
HOUSING / SURFACE TREATMENT
U - Aluminum, Powder Epoxy, Black
R - Remote Mount Feedback Sensor
S - Explosionproof, Stainless Steel Enclosure ( N Connections Only
$\square$ FUNCTION
S - Single Acting
D - Double Acting, (Note Available on Explosionproof Enclosures) See Note 1

## SHAFT

23 - NAMUR, VDI/VDE 3845, Rotary

## COVER

1 - Flat Top, All Options ( See Note 2) ** Only option for Explosionproof
2 - Dome Indicator, Red/Green, (General Purpose/IS Only) See Note 2
3 - Flat Top, Green/Black Flat Indicator, (General Purpose/IS Only) See Note 2

## TEMPERATURE / SEALS

Z - Standard Temperature $-20^{\circ} \mathrm{C}$ to $85^{\circ} \mathrm{C}\left(-4^{\circ} \mathrm{F}\right.$ to $185^{\circ} \mathrm{F}$ )
Q - Low Temperature $-40^{\circ} \mathrm{C}$ to $85^{\circ} \mathrm{C}\left(-40^{\circ} \mathrm{F}\right.$ to $185^{\circ} \mathrm{F}$ )
$\square$ INPUT SIGNAL / PROTOCOL
N $-4-20 \mathrm{~mA} /$ None
H $-4-20 \mathrm{~mA} / \mathrm{HART}$

## FEEDBACK OPTIONS

X - No Feedback Options
T - 4-20mA Feedback Transmitter Only
S - Switches, Mechanical, SPDT + 4-20mA Transmitter, (See Note 3)
N - NAMUR, V3 Type Sensor, P\&F NJ2-V3-N + 4-20mA Transmitter, (See Note 3)
N - Limit Switches, Proximity, SPDT + 4-20mA Transmitter, (See Note 3)

OPTIONS / ADDITIONAL ELECTRONICS
0 - Standard Diagnostics
1 - Advanced Diagnostics, ( Available in Model 92 Only )
ACCESSORIES
X - No Accessories
M - Gauge Block, 1/8" G, ( 2 Gauges Included) See Note 4
N - Gauge Block, 1/8" NPT, (2 Gauges Included) See Note 4

## NOTES:

1) If you order double acting, you do not need to order a gauge block. Comes with 2 gauges, Stainless Steel with Brass internals.
2) Cover options are valid only for General Purpose, Intrinsically Safe, and Class I Division 2, Nonincendive, ( G, I, and N Approvals options ).
3) Switches are not available in explosionproof enclosure.
4) Gauge blocks are only needed for the General Purpose, Intrinsically Safe, and Class I Division 2, Non-incendive options ( Approvals G, I and N).

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Figure 1

## 6. Principle of operation

The APEX A9000 positioner is a digital positioner with various options. The positioner consists of three main modules:

1. The microprocessor-based electronic control module includes direct local user interface switches
2. The piezo valve-based electro- pneumatic converter module
3. The infinite resolution valve position sensor.

The basic positioner operation is best understood by referring to figure 1. The complete control circuit is powered by the two-wire, 4-20 mA command signal. The analog 4-20 mA command is passed to the microprocessor, where it is compared to the measured valve stem position. The control algorithm in the processor performs control calculations and produces an output command to the piezo valve, which drives the pneumatic amplifier. The position of the pilot valve in the pneumatic amplifier is measured and relayed to the inner loop control circuit. This two-stage control provides for more responsive and tighter control than is possible with a single stage control algorithm. The pneumaticamplifier controls the airflow to the actuator. The change of pressure and volume of the air in the actuator causes the valve to stroke. As the valve approaches the desired position, the difference between the commanded position and the measured position becomes smaller and the output to the piezo is decreased. This, in turn, causes the pilot valve to close and the resulting flow to decrease, which slows the actuator movement as it approaches, the new commanded position. When the valve actuator is at the desired position. the pneumatic amplifier output is held at zero, which holds the valve in a constant position.

## 7. Mounting and installation

### 7.1 General

Before starting installation, inspect the digital positioner for any transit damages.

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After installation, ensure all screw connections are tightened correctly and all moving parts are free from excessive friction.

## NOTE!

All products that are covered by an ATEX Certification number ending with an " X ", special care must be taken when cleaning the surface of the product.
"The enclosure must be cleaned with a damp cloth due to static electricity for plastic windows/surfaces"
For securing covers and lids, it's important to use the correct torque:
Product $\quad$ Size (screw) $\quad$ Torque Nm

| I/P cover APEX A9000 | M4 | $0,65 \mathrm{Nm} \quad+/-15 \%$ |  |
| :--- | :--- | :--- | :--- |
| APEX A9000 | M5 | $1,20 \mathrm{Nm} \quad+/-15 \%$ |  |
| F5EX and XCL / XML / XV | M6 / M8 | 7 Nm |  |

Covers (thread on) for APEX A9000 EX, D3EX, Tighten fully and secure Exhaust ports
Apex A9000 exhaust actuator through a hole in the backside, covered by a plate.

Apex A9000 Explosion proof has $2 \times$ exhaust ports, located on the flat areas. Make sure that both these ports are not left open, facing up or side wards.

Protected by a proper bleeder cap or a fitting with short tube ( $\geq \varnothing 4 \mathrm{~mm}$ inner dia, max 80 mm long) facing downwards


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### 7.2 Dimensional drawings



### 7.3 Mounting

NOTE. If the positioner is installed in a hazardous environment, it must be of a type approved for this purpose.
The Apex A9000 positioner, all versions, has an ISO F05 footprint, A. The holes are used to attach the Apex A9000 to the mounting bracket B. Please contact Flowserve or your local distributor representative with actuator specifics for the proper mounting bracket and hardware.

It is important that the positioner's spindle, that transfer the actuator movements, are correctly mounted. Any tension between these parts can cause incorrect operation and abnormal wear.

## Assembly Example:



## Rotary actuators

Mounting the Apex A9000 positioner on a quarter-turn actuator (closed or open by spring)
The mounting of a pneumatic double-piston part-turn valve actuator (inaccordance with VDI/VDE 3845) is described as an example by using the following equipment:

Quarter-turn valve actuator: Rack \& pinion or scotch yoke, closed or open by spring.

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## Rotary actutaors VDI/VDE 3485 (Namur)

Mount bracket $\mathbf{1}$ to positioner. Secure with $4 \times \mathrm{M} 6$ screws 2 .
Fit positioner on actuator and secure with $4 \times$ screws 3 .
Install tubing 4 between actuator and positioner.

(Figure 6)

## Mounting the positioner

Place the positioner (1) onto themounting block (2) of the actuator using four screws (3) Ensure the coupler fits on to the shaft of the quarter-turn connection on the part-turn valveactuator.

## 8. Tubing positioner to actuator

After mounting has been completed, tube the positioner to the actuator using the appropriate compression fitting connectors:

Air connections: 1/4" NPT (standard air connection).
Auxiliary power: Pressurized air or permissible gases, free of moisture and dust in according with IEC 770 or ISA 7.0.01.

Pressure range: $1,5-6 \operatorname{bar}(30-90 \mathrm{psi})$. For connecting the air piping, the following notes should be observed:

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1. The positioner passageways are equipped with filters, which remove me- dium and coarse size dirt from the pressurized air. If necessary, they are easily accessible for cleaning
2. Supply air should meet IEC 770 or ISA
7.0.01 requirements. A coalescing filter should be installed in front of the supply air connection (Figure 8). Now connect the air supply to the filter, which is connected to the Apex A9000 positioner.
3. With a maximum supply pressure of 6 bar ( 102 psi ) a regulator is not required.
4. With an operating pressure of more than $6 \mathrm{bar}(90 \mathrm{psi})$, a reducing regulator is required.

The flow capacity of the regulator must be larger than the air consumption of the positioner ( $7 \mathrm{Nm}^{3} / \mathrm{h} @ 6 \mathrm{bar} / 4,12 \mathrm{scfm}$ @ 90 psi).
5. Connect the outlet connector (Figure7) of the positioner with tubing, independent of the action (direct or reverse). On explosion proof housing air connections are marked S,C+ and C-, plug C- port with proper fitting.


Figure 7

## 9. Wiring and grounding guidelines

Electrical connections: signal cable with cable passage ( $1 / 2^{\prime \prime}$ NPT, or M20 $\times 1,5$ ) to terminals $2 \times 2,5 \mathrm{~mm}$.

Input signal: 4-20 mA NOTE: Observe the minimum requirements of voltage and equivalent electrical load:

The performance is ensured only for a minimum input current of 3.6 mA For wiring, the following notes should be observed:

NOTE: The input loop current signal to the Apex A9000should be in shielded cable. Shields must be tied to a ground at only one end of the cable to provide a place for environmental electrical noise to be removed from the cable. In general, shield wire should be connected at the source. (Figure 8).

Connect the $4-20 \mathrm{~mA}$ current source to terminals +1 and -2 , see connection table.


Figure 8 Connections

| Connection | Description |
| :---: | :--- |
| +1 | Input $+4-20 \mathrm{~mA}$ |
| -2 | Input $-4-20 \mathrm{~mA}$ |
| $\mathbf{~}$ | Pneumatic output <br> signal (outlet) |
| $\vdots$ |  |
| $\mathbf{~}$ | Air supply |

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### 9.1 Grounding screw

The grounding screw, located inside the positioner cover, should be used to provide the unit with an adequate and reliable earth ground reference. This ground should be tied to the same ground as the electrical conduit. Additionally, the electrical conduit should be earth grounded at both ends of its run. The grounded screw must not be used to terminate signal shield wires.

### 9.2 Electromagnetic compatibility

The Apex A9000 digital positioner has been designed to operate correctly in electromagnetic (EM) fields found in typical industrial environments. Care should be taken to prevent the positioner from being used in environments with excessively high EM field strengths (greater than $10 \mathrm{~V} / \mathrm{m}$ ). Portable EM devices such as hand-held two-way radios should not be used within 30 cm of the device. techniques of the control lines, and route control lines away from electro-magnetic sources that may cause unwanted noise.

An electromagnetic line filter can be used to further eliminate noise.
In the event of a severe electrostatic discharge near the positioner, the device should be inspected to ensure correct operability. It may be necessary to recalibrate the Apex A9000 positioner to restore operation.

Ensure proper wiring and shielding


Figure 9. Compliance voltage

### 9.3 Compliance voltage

Output compliance voltage refers to the voltage limit the current source can provide. A current loop system consists of the current source, wiring resistance, barrier resistance (if present), and the Apex A9000 impedance.

The Apex A9000 requires that the current loop system allow for a 8.0-9.4 VDC drop across the positioner at maximum loop current.

CAUTION: Never connect a voltage source directly across the positioner terminals. This could cause permanent circuit board damage.

In order to determine if the loop will sup- port the Apex A9000, perform the following calculation:
Voltage $=$ Compliance Voltage $\left(@ C_{u r r e n t ~}^{\text {max }}\right.$ ) $)-$ Current $_{\max }\left(R_{\text {bamier }}+R_{\text {wiee }}\right)$
To support the Apex A9000 the calculated voltage must be greater than 9.4 VDC for Apex A9000 HART and 8 VDC for non-HART.

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Example: DCS Compliance Voltage $=19 \mathrm{~V}, \mathrm{R}_{\text {barrier }}=300 \Omega, \mathrm{R}_{\text {wire }}=25 \Omega$ and Current $\max =20 \mathrm{~mA}$
Voltage $=19 \mathrm{~V}-0.020 \mathrm{~A}(300 \Omega+25 \Omega)=\underline{12.5 \mathrm{~V}}$
This system will support the Apex A9000, as the voltage 12.5 V is greater than the required 8 VDC for non-HART and 9.4 VDC for HART.

## 10. Operation / Mode 90

### 10.1 General

The Apex A9000 is operated by the yellow button. Depending on desired action, press the button:

- during a number of seconds (Ex 5 sec ):

Or

- a number of times. (Ex x 3 )


### 10.2 Startup

Connect Air supply and a mA-simulator to the positioner.
Warning: During calibration, the actuator may stroke unexpectedly.
$5 \mathbf{s e c}$. Press the button for 5 sec . (Re- lease the button when the three LED:s start to flash alternately). The calibration starts, the actuator goes go to max. and min. position and calculates the control parameters.

The Calibration procedure will take between 30 seconds and some minutes depending on actuator size. The three LED's will flash alternately during calibration. After calibration all the three LED's are lit for a moment.

A successful calibration is indicated by yellow or green LED:
Green LED flashes $=$ In service
Yellow LED flashes $=$ In service.
The unit vents in max or min position.
An unsuccessful calibration by error codes:

- Apex A9000 does not reach setpoint

For other indications, see error codes on page 30.

### 10.4 Set Direct or Reverse action

Note! For safety reason, this operation has to be done max 5 minutes after calibration. If time has run out, or if power is disconnected during the five minutes, perform a new calibration, before changing thedirection.

Apply 4 mA . If valve is in right position, then check the position over the whole range ( $8,12,16$ and 20 mA ) If the direction needs to be changed, press the $\bigcirc_{\mathrm{X} 3}$ calibration button 3 times, and the direction will change.
Check operation at 4-8-12-16 and 20 mA .

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### 10.5 Show gain setting

If the actuator position is unstable or self-oscillating after calibration, the gain can be adjusted.
Gain can be set from $\mathbf{A}$ (lowest) to $\mathbf{G}$ (highest). Default is $\mathbf{D}$.
To show the current gain setting, press $\bigcirc_{\text {X4 }}$ the calibration button 4 times.
To indicate the current setting, the LED's flashes according to the following:
Y R R
LED's show: $O \bigcirc \bigcirc$ gain is set to " G " (Highest)


LED's show Y R Y

Y R G
LED's show
$\mathrm{O} O$
Y G
LED's show OO gain is set to "D" (Default)
LED's show $O$ O o gain is set to " C " Y G Y
LED's show $O O O$ gain is set to " B " Y G R
LED's show O O gain is set to "A" (Lowest)
The gain code sequence is repeated 5 times

| Button functions: |
| :--- |
| Press 5 sec = Calibration |
| Press x 3 = Direct/reverse action |
| Press x 4 = Show gain setting |
| Press x 5 - x 11 = Change gain |
| setting |

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### 10.6 Change of gain setting

To lower the gain, press the calibration button: 7,6 or 5 times ( $5=$ lowest) ○x11"G" (Highest)

To increase the gain (if actuator is moving to slow), press the button 9,10 or 11 times ( $11=$ highest) to increase the gain.


○ $x 9$ "E"
The LED's flashes alternately when the button is pressed.
After gain change the LED's show the gain code (see 9.3) five times.
x8 "D" (default) $\qquad$
The default value after first calibration is $\mathbf{D}$.
S7"C"
○ $x 6$ "B"
x5 "A" (Lowest)
After this, setting the gain is complete.


## 11. Operation / Model 92 with LCD

The positioner is controlled using the five pushbuttons and the display, which are accessible when the aluminium cover is removed

Out of service Manual

BASIC MENU MAN/AUTO
unprotected


Use the
 pushbuttons to browse through the menus and sub-menus.
The main menu is divided up into a basic menu and a full menu, see page 21.

### 11.2 Other functions

## ESC

Exit the menu without making any changes (as long as any changes have not been confirmed with OK). FUNC
To select function and change parameters.
OK
To confirm selection or change of para-meters.
MENU INDICATOR
Displays the position of the current menu row in the menu.
IN SERVICE
The positioner is following the input sig-nal. This is the normal status when the positioner is working.
OUT OF SERVICE
The positioner is not following the input signal. Critical parameters can be changed.
MANUAL
The positioner can be adjusted manually using the pushbuttons. See section
"Man/Auto", page 24".
UNPROTECTED
Most of the parameters can be changed when the positioner is in the"Unprotected" position. However, critical parameters are locked when the positioner is in the "In service" position.

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### 11.3 Menu indicator

There are indicators at both sides of the display window and they indicate as follows:

Flashing in position Out of Service
FULL MENU CALIBRATE

Flashing in position Manual
Flashing in position Unprotected
The indicators on the right-hand side show the position in the current menu.

### 11.4 Menus

To display the menus you can select:

- Basic menu, which means you can browse through four different steps
- Full menu, which comprises ten steps. Use the Shift Menu to browse through the steps

Full Menu can be locked out using a passcode.
The main menus are shown on the next page and the sub-menus on thesubsequent pages.

### 11.5 Changing parameter values

Change by pressing flashing.


Press
 to step to the desired figure. Confirm by pressing OK.

A change can be undone by pressing the ESC button, which returns you to the previous menu.

## FLOWSERVE

### 11.6 Menu system



The menus are described on the following pages.



### 11.7 First start

Calibrate in the basic menu is displayed automatically the first time the power is applied, and can be selected from the basic/main menu at any later time.

A complete auto-calibration takes about 2 minutes and includes end limitcalibration, auto-tuning and a check on the speed of movement. Start the automatic calibration by selecting Auto-Cal and then answer the questions on the display by pressing OK or the respective arrow. The menu is described on the next page.

## Calibration error messages

If a fault occurs during calibration, one of the following error messages can be displayed:
No movement/press ESC to abort Typically the result of an air delivery issue to the actuator, or incorrect mounting and/or linkage arrangement. Check for proper supply air to the positioner, pinched tubing, proper actuator sizing, proper linkage and mounting arrangement.

Pot un-calibrated/press ESC to abort The potentiometer has been set to an illegal value. The potentiometer is aligned using the Calibrate - Expert cal - pot Menu. The calibration sequence must be restarted after the fault is corrected.


The contents of the menu are shown on the next page. The various menu texts are described below.

| Auto-Cal | Auto-tuning and calibration of end positions <br> Start tune |
| :--- | :--- |
| Starts the tuning. Questions/commands are displayed during calibration. Select the type of <br> movement, function, etc. with and confirm with OK as shown in the chart on the next <br> page. |  |
| Lose prev value? OK? <br> Direction? Air to open/ <br> Air to close | A warning that the value set previously will be lost (not duringthe first auto-tuning). |
| In service? Press OK | Calibration finished. Press OK to start positioner functioning. (If ESC is pressed, the positioner <br> assumes <br> the "Out of service" position but the calibration is retained). |
| $\frac{\text { TravelCal }}{\text { Start cal }}$ | Calibration of end positions |
| Start end position calibration. |  |


| Lose prev value? OK? | A warning that the previously set value will be lost. <br> Confirm with OK. |
| :--- | :--- |
| The calibration sequence starts |  |
| In service? Press OK | Calibration finished. Press OK to start positioner functioning. (If ESC is pressed, the positioner <br> assumes the "Out of service" position but the calibration is retained). |

## Perform

Setting gain
Normal A,B,C,D,E,F,G See Page 17 for details on how to set gain.

## ExpertCal

Set point LO: Use the calibrator set to 4 Ma (or set another value on the display). Press OK.
Set point HI: Use a calibrator of 20 mA (or set another value on the display). Press OK.
Transmitter: Connect 10-28VDC. Connect an external mA meter to the loop. Read low value on mA meter and adjust with up/down key. Press OK to set low value.
Repeat procedure to set High value. Also see video on www.flowserve.com
Pot: Potentiometer setting, see section 8. Also see video on www.flowserve.com
Full reset: Resets all set values.

## Optional

Pressure LO: Use a supply of 2 bar (30 psi) (or set another value on the display). Press OK. Pressure read out only possible on Apex A9000 with built in pressure sensor.

Pressure HI: Use a supply of 7 bar (105 psi) (or set another value on the display). Press OK. Pressure read out only possible on Apex A9000 with built in pressure sensor.

## FLOWSERVE

The menu contents are shown in the figures on the right and the texts are described below:


Pos Shows current position
Set\&pos Set point and position

Set\&dev Set point and deviation

Temp Shows current temperature

Statistics
n cycles
Shows number of movements (turns)

Acc travel Shows accumulated movement
mean dev Shows accumulated deviation (absolute values) in \%
\# of reset Shows number of resets
runtime Shows accumulated runtime since last reset
Extr temp Shows extreme min and max temperature

Histogram Shows position and time for PV

Alarms
Displays tripped alarms
\# of resets Number of Resets
Reset stat Resets Statisctics
PosGraph Shows position with graph



The Man/Auto menu is used to change between manual and automatic modes.

The menu contents are shown in the figures on the right and the various texts are described below:

AUS, OK = MAN
Positioner in automatic mode


When changing between MAN and AUT mode, the OK button must be pressed for 3 seconds.

MAN, OK = MUT
Positioner in manual mode
In the MAN mode, the value of POS can be changed using The push- buttons increase/decrease the value in steps. The value can also be changed in the same way as for the other parameter values, as described on page 20.

## Other functions

C+ can be fully opened by pressing $\qquad$ and then immediately OK simultaneously.

C+ can be fully opened for blowing clean by pressing
 and OK simultaneously.


The Shift Menu is used to choose between the basic menu and the full menu.
The menu contents are shown in the figures on the right and the various texts are described below:

No Full menu selected.
Yes Basic menu selected.

Full Menu can be locked with a passcode, see Setup menu.



The Status Menu is used to select whether or not the positioner is in service.
The menu contents are shown in the figures on the right and the various texts are described below:

| o o service | Not in service. <br> Flashing indicator in upper left-hand corner of display. |
| :--- | :--- |
| in service $\quad$Positioner in service. <br> Critical parameters cannot be changed. |  |

FULL MENU
SETUP

The Setup Menu is used for various settings.
The menu contents are shown in the chart on the next page and the various texts are described below:


| $\frac{\text { TRVL range }}{0 \%=0.0 \%}$ | Setting end positions |
| :---: | :---: |
|  | Select Out of Service. <br> Set percentage value for desired end posi- tion (e.g. 3\%). |
| Set 0\% |  |
|  | Connect calibrator. Move forward to desired end position (0\%) and press OK. |
| 100\%=100.0\% | Select Out of Service. |
| Set 100\% | Set percentage value for desired end posi tion (e.g. 97\%). |
|  | Select In Service. <br> Connect calibrator. Move forward to desired end position (100\%) and press OK. |
| $\frac{\text { Trvl ctrl }}{\text { Set low }}$ | Behavior at set end position <br> Choose between Free (go to mechanical stop), Limit (stop at set end position), and Cut off (go directly to mechanical stop at set end position). |
|  |  |
| Set high Values |  |
|  | Select position for Cut off and Limit at the respective end positions. |
| Passcodes Full menu Write prot Expert Fact set | Setting passcodes for various functions <br> Passcode for access to full menu. <br> Passcode for removing write protect. <br> Passcode for access to Expert menu (TUNING). <br> Passcode to return to default values applicable when positioner was delivered. |
|  |  |
|  |  |
|  |  |
|  |  |
| Numbers between 0000 and 9999 can be used. |  |
| Appearance Language Units | On display Select menu language. Select units. |
|  |  |
|  |  |
| Def. Display | Select value(s) to be displayed during service. The display reverts to this value 10 minutes after any change is made. |
|  |  |
| Start menu | Start in Basic menu or |
| Start Logo | Shows Flowserve Logo |
|  |  |
| Orient | Orientation of text on display. |
| Devicedata HW rev SW rev Capability |  |
|  |  |
|  | - General Parameters |
| HART | Menu with HART parameters. Only amendable with HART communicator. It is possible to read from display. |
|  | TUNING |
| The menu contents are shown in the chart on the next page and the various texts are described below: |  |
| Close time | Minimum time (Min 0.005) from fully open to closed. |
| Open time | Minimum time (Min 0.05) from closed to fully open. |
| Deadband | Setting deadband. Min. 0.2\%. |
| Expert | Advanced settings. |
| Control | See explanations below. |
| Togglestep | Test tool for checking functions. Overlays a square wave on the set value. |
| Self test | Internal test of processor, potentiometer, etc. |

## FLOWSERVE

Leakage $\quad$ Air leakage in actuator/tubing can be compensated by settings.

Undo You can read last 20 changes.

## $P, I, D$ and $K, T i, T d$ parameters

If one of the gains is changed, the corresponding value in the other gain set is changed accordingly.

## Spring adjust

The spring adjust function compensates the airflow linearly with the actuator C+ chamber volume (for a constant position error), so that low volumes get less flow. This is needed for linear single-acting actuators, where a low C+ volume means that the actuator spring is extended, its force is reduced, and less flow is needed for stable position change.

## Fiction

High or Low: Select High for high friction valve actuator assemblies such as plug valves

|  |  | Full Menu Alarms | $\nu$ |
| :---: | :---: | :---: | :---: |
| Deviation | Alarm generated when deviation occurs |  |  |
| On/Off | Alarm on/off. |  |  |
| Distance | Allowed distance before alarm is generated. |  |  |
| Time | Total deviation time before alarm is generated. |  |  |
| Alarm out | Select ON/OFF offers output on terminals. |  |  |
| Valve act | Behaviour of valve when alarm is generated. |  |  |
| Limit 1 | Alarm above/below a certain level. |  |  |
| On/Off | Alarm on/off. |  |  |
| Minipos | Setting of desired min. positionSetting of desired max.position |  | See Diagram Below |
| Maxpos |  |  |  |
| Hysteresis | Select ON/OFF offers output on terminals. |  |  |
| Alarm on |  |  |  |  |
| Valve act | Behaviour of valve when alarm is generated |  |  |

## FLOWSERVE

## $\underline{\text { Limit } 2} \underline{\text { See Limit } 1 .}$



| temp | Alarm based on temperature. |
| :--- | :--- |
| On/Off | Temperature alarm on/off. |
| Low temp | Temperature low limit setting |
| High temp | Temperature high limit setting |
| Hysteresis | Allowed hysteresis. |
| Alarm on | Select ON/OFF offers output on terminals. |
| Valve act | Behaviour of valve when alarm is generated |

## Valve act

| No action | Alarm generated only. Operations no affected. |
| :--- | :--- |
| Goto open | C+ gives full pressure and valve moves to fully open position. Positioner <br> changes to position Manual. |
| Goto close | C- gives full pressure and valve moves to fully closed position. Positioner changes to <br> position Manual. |

Manual Valve stays in unchanged position. Positioner moves to position Manual.

## FLOWSERVE



The menu contents are shown in the chart below.

The default values that were set on delivery can be reset using the Fact Set menu. Values from calibration and from other settings will then be lost.


FLOWSERVE
READ

${ }^{(*)}$ appear if Linear is set
(**) appear if pressure sensors exist
(X) Position is shown in upper row (PID, kTiTd)

## 12. Limit switches \& 4-20 mA transmitter (Optional)

## Caution!

The installation of electricalequipment in hazardous areas must comply with the procedures contained in the certificates of conformity. Country specific regulations may apply.

Electrical safety is determined only by the power supply device.

### 12.1 General

Apex A9000 can be equipped with optional plug in modules for limit switches and/or 4-20 mA feedback transmitter.

### 12.2 Model selection

See Apex A9000 model code

### 12.3 Priciple of operation

The stroke of the actuator/valve is picked up by the potentiometer inside the Apex A9000. Movement is transferred from actuator via lever or shaft coupling. Cams/vanes mounted on the positioner shaft actuate limit switches 1 and 2 . The switching point can be adjusted on each cam/vane.

The position transmitter converts actual position into a $4-20 \mathrm{~mA}$ output signal. This loop requires an external 12-25 VDC power supply.

### 12.4 Installation

Caution! Turn off power and air supply before starting the installation.

## Important!

For Apex A9000 installed in hazardous areas, maintenance and repair must only to be made by authorized and trained staff.

-Remove cover, indicator if present and inner plastic cover.
-Check that spacers are installed on the printed circuit board.
-Carefully install feedback board into its position on the pins.
-Secure it with two (2) screws.

## FLOWSERVE

-Install cam assembly on the shaft, if feedback card has mechanical micro switches, be careful to not damage switch arms.
-Install plastic inner cover.
-Adjust cams/vanes to ensure proper switching.
-Secure cam/van position by locking them with two (2) screws.
-Calibrate 4-20 mA transmitter, (see next page).
-Install cover


### 12.5 Apex A9000 Calibration of 4-20 mA input signal and/or 4-20mA feedback transmitter

- Press and hold button while switching on power to the Apex A9000, keep the button pressed for 6 sec . The eeprom will now be erased, and then all three LEDs are lighted. The LEDs will start to flash yellow-red. This starts FACTORY MODE!


## To calibrate 4-20 mA input signal

- Apply 4.0 mA input signal and then push the button three (3) times until all LEDs are lighted. The LEDs will now start flash yellow-red again.

Apply 20.0 mA input signal and then push the button three (3) times until all LEDs are lighted.

## To calibrate 4-20 mA transmitter output signal

Note! If no transmitter board is installed the LEDs will start flash yellow-yellow and the unit is ready for continued calibration. If there is a transmitter board installed the LEDs will start flash yellow-green.

The feedback transmitter output signal on pin 9 and 10 will now follow the input signal instead of the position. Apply 4.0 mA input signal. Measure the output sig- nal and adjust the input signal up/down until the output signal is 4.0 mA . Push the button three times until all LEDs are lighted. The unit will now start to flash yellow-green again.

## FLOWSERVE

The output signal on pin 9 and 10 will continue to follow the input signal instead of the position. Apply 20.0 mA input signal. Measure the output signal and adjust the input signal up/down until the output signal is 20.0 mA . Push the button three times until all LEDs are lighted.

The LEDs will start flash yellow-yellow and the unit is ready for continued calibration.
Press the button for 5 sec until the LEDs start alternating, Apex A9000 starts to calibrate stroke.
After calibration the unit will start running in normal operation.

## 13. Trouble shooting

### 13.1 Apex A9000 Normal operation

| G | Normal operation. |  |
| :---: | :--- | :--- |
| Y | Valve fully closed or open <br> "Cut off" enabled. |  |

13.2 Calibration

| RGG <br> (No movement) | No air supply or <br> shaft do not move. | Check air supply <br> Check shaft movement. |
| :---: | :--- | :--- |
| RYG |  |  | Pot not calibrated. $\quad$ Calibrate the pot..

### 13.3 APEX A9000 symptoms and solutions

| Failure | Probable Cause | Corrective action |
| :--- | :--- | :--- |
| No LED is flashing. | Current source below $3,6 \mathrm{~mA}$. <br> Incorrect wiring polarity. | Verify current source supplies at <br> least $3,6 \mathrm{~mA}$. Check wiring for <br> correct polarity. |
| Valve position reading <br> is not what is expected. | Stem position sensor mounting <br> is off 180 degrees. <br> Apex A9000 not calibrated. <br> Tight shutoff MPC (Minimum <br> position cutoff) is active. | Reposition sensor. <br> Calibrate Apex A9000. |
| Apex action. |  |  |
| in wrong direction. |  |  |$\quad$| Change direction |
| :--- |
| (Section 10.4). |

## 14. Maintenance/service

When carrying out service, replacing a circuit board, etc., it may be necessary to remove and refit various parts of the positioner. This is described on the following pages.

Read the Safety Instructions on page $\mathbf{3}$ before starting work on the positioner. Cleanliness is essential when working with the positioner. Contamination in the
air ducts will infallible lead to operational disturbances. Do not disassemble the unit more than that described here.

Do not take the valve block apart because its function will be impaired.
When working with the Apex A9000 positioner, the work place must be equipped with ESD protection before the work is started.

Always turn off the air and electrical supplies before starting any work.

When upgrading electronically parts inside a Accord positioner approved for installation in Hazardous locations special procedures apply, permission from ACCORD/Flowserve is required prior to the start of work.

Please contact a Flowserve office for information regarding proper procedures.

## Disassembling Apex A9000

Removing cover and inner cover

- Loosen and remove the screws A and remove the cover. When mounting cover - see page 10.

- Pull off the arrow pointer, B, using a small screw driver.

- Remove the screws C , pull the inner cover slightly in the direction of the arrow, and remove the cover. Do not remove the filter plug.


## FLOWSERVE

## Disassembling Apex A9000 Explosion Proof

Removing cover and inner cover

- Unscrew the screw A and remove the cover. When mounting cover - see page 10.

- Unscrew the three screws B, lift the circuit board.

- Loosen the cables C and D.



## FLOWSERVE

- Unscrew the two screws E and F and remove the Modulator.



## FLOWSERVE

15. Spare parts: General Purpose/IS/non-incendive Enclosures


For Instrinsically Safe/ General Purpose/non-incendive

| Item \# | Part Number | Description | Remarks |
| :---: | :---: | :---: | :---: |
| 20 | X05058 | Housing | N/A as part |
| 1 | X05012 | Lever arm set |  |
| 2 | X05013 | Potentiometer assy. Complete |  |
| 3 | X05014 | Shaft, VDI/VDE 3845 Rotary |  |
| 4 | X05015 | Air relay assy. Ind. O-rings, screws, standard temp |  |
| 4 | X05016 | Air relay assy. Ind. O-rings, screws, low temp |  |
| 5 | X05017 | Electronics |  |
| 5 | X05018 | Electronics, Intrinsically Safe | Ex ia |
| 5 | X05019 | Electronics, HART | HART |
| 5 | X05020 | Electronics, HART, Intrinsically Safe | Ex ia, HART |
| 6 | X05021 | Electronics (For LCD Apex 92) |  |
| 6 | X05022 | Electronics Intrinsically Safe (For Apex 92) | Ex ia |
| 6 | X05023 | Electronics, HART ( For Apex 92) | HART |
| 6 | X05024 | Electronics, HART Intrinsically Safe (For Apex 92) | Ex ia,HART |
| 7 | X05025 | Indicator, flat assy, Complete |  |
| 8 | X05026 | Indicator, dome style assy. Complete |  |
| 9 | X05027 | Front cover, no indicator, black, ind. Screws |  |
| 10 | X05028 | Front cover w/ LCD, no indicator, black, ind. Screws |  |
|  | X05029 | Front cover, for indicator/dome, black, ind. Screws |  |
| 11 | X05030 | Front cover w/, for indicator/dome, black, ind. Screws |  |
| 12 | X05031 | Inner cover assy. |  |
| 13 | X05032 | Inner cover assy, LCD version |  |
| 14 | X05033 | 4-20mA transmitter only |  |
| 14 | X05034 | Mechanical switches assy. Comp (incl. cams, screws) |  |
| 14 | X05035 | Proximity switches assy. Complete |  |
| 14 | X05036 | P\&F NJ2-V3-N sensor assy. Complete |  |
| 14 | X05037 | P\&F SJ2 S1N sensor assy. Complete |  |
| 14 | X05038 | P\&F SJ2 SN sensor assy. Complete |  |
| 14 | X05039 | P\&F SJ2N sensor assy. Complete |  |
| 15 | X05040 | Gauge block B $1 / 4$, NPT, $1 / 4$ " NPT, 1/8" ${ }^{\text {" }}$ NPT, no gauges |  |
| 15/16 | X05040 | Gauge block B $1 / 4$, NPT, $1 / 4{ }^{\prime \prime}$ NPT, 1/8" NPT, 1 Gauge (SS/Brass) |  |
| 15/16 | X05040 | Gauge block B $1 / 4$, NPT, $1 / 4{ }^{\prime \prime}$ NPT, 1/8"NPT, 2 Gauges (SS/Brass) |  |
| 19 | X05041 | Double acting module incl. 2 gauges |  |
| 21 | X05042 | Plug and cable gland kit, black |  |
|  | X05043 | Seal and O-ring kit |  |
|  | X05044 | Screw and washer kit |  |

## FLOWSERVE

16. Spare Parts: Explosion Proof Enclosure


For Explosion Proof Version Apex 90 and 92

| Item\# | Part Number | Description | Remarks |
| :---: | :--- | :--- | :--- |
|  |  | Housing | N/A as part |
| $\mathbf{1}$ | X05045 | Cover, large | N/A as part |
| 9 | X05046 | Cover, terminals | N/A as part |
| 6 | X05047 | Potentiometer complete, including spring, holder,cable |  |
| 13 | X05048 | Shaft, VDI/VDE 3845 Rotary |  |
| 7 | X05049 | Air relay, Ind. O-rings, screws, standard temp |  |
| 7 | X05050 | Air Relay, Ind. O-rings, screws, Iow temp version |  |
| 5 | X05051 | Electronics, single button Apex 90 ver. | HART |
| 5 | X05052 | Electronics + 4-20 mA transmitter, Single button Apex 90 ver. | HART |
| 5 | X05053 | Electronics, HART, Single button Apex 90 ver. |  |
| 5 | X05054 | Electronics, HART+4-20 mA transmitter, Single button Apex 90 ver. |  |
| 4 | X05055 | Electronics, For LCD, Apex 92 ver. |  |
| 4 | X05056 | Electronics + 4-20 mA transmitter for LCD, Apex 92 ver. |  |
| 4 | X05057 | Electronics, HART for LCD, Apex 92 ver. |  |

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